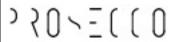


Computational Approaches to Conceptual Blending (part II)

Amílcar Cardoso

Autumn School on Computational Creativity Porvoo, Finland, November 2013







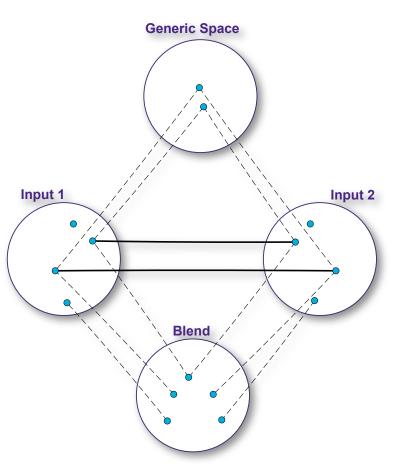
Divago

Given:

- Two input Domains (Mental Spaces)
- One Generic Space Domain
- Produces:

, 50 × 5((0

Blend Domain

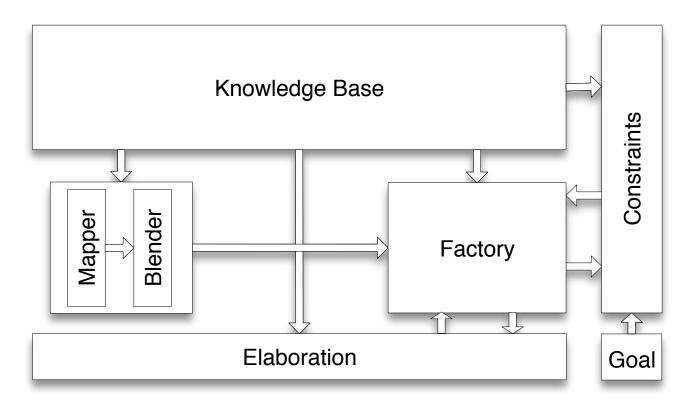




2

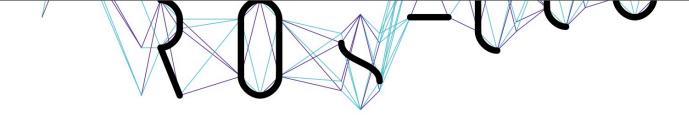


Divago Architecture



> 30 > E((0



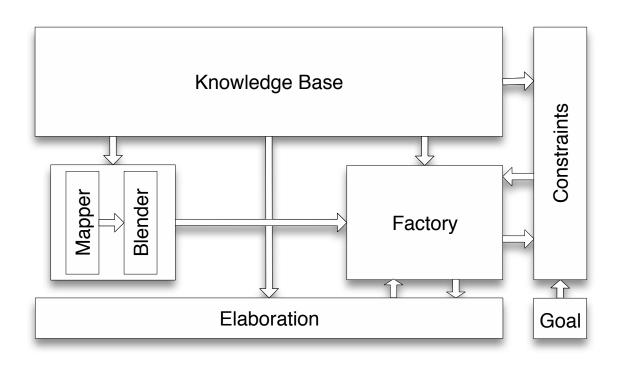


Knowledge Base

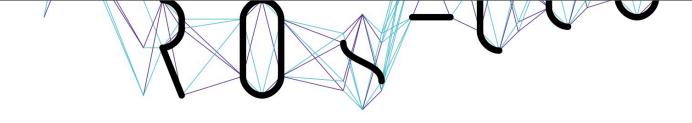
- Composed by Domains
- Domain:

, 50 > E((0

- Concept Map
- set of Instances
- set of Rules
- set of Frames
- set of Integrity Constraints





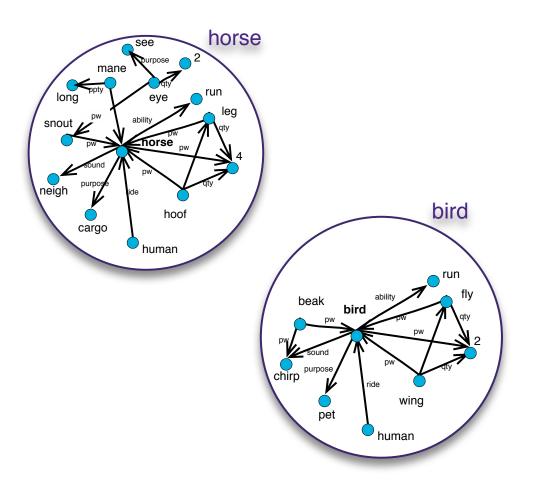


Knowledge Base

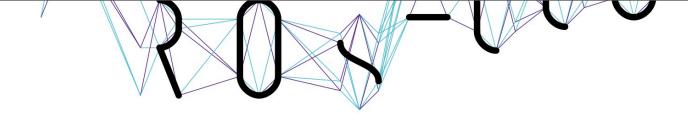
- Composed by Domains
- Domain:

, 50 × 5((0

- Concept Map
- set of Instances
- set of Rules
- set of Frames
- set of Integrity Constraints







6

Knowledge Base

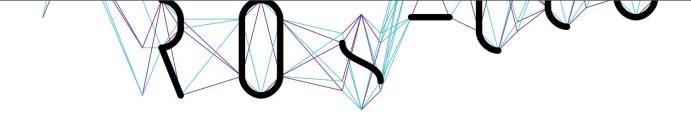
- Composed by Domains
- Domain:

> 50 > E((0

- Concept Map
- set of Instances
- set of Rules
- set of Frames
- set of Integrity Constraints

 $\begin{aligned} frame(transport_means(X)):\\ carrier(X, people) &\longleftarrow have(X, container) \land have(X, Y) \land\\ purpose(Y, locomotion) \land drive(_, X) \end{aligned}$





Knowledge Base

- Composed by Domains
- Domain:

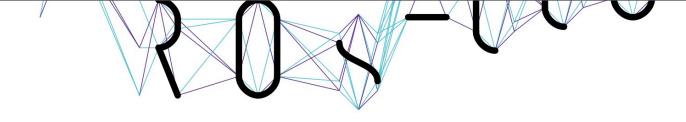
> 50 > E((0

- Concept Map
- set of Instances
- set of Rules
- set of Frames
- set of Integrity Constraints

 $\begin{aligned} frame(new_ability(d1)): \\ new_ability(X, A) &\longleftarrow ability(X, A) \land not \ rel(d1, ability(X, A)) \land \\ purpose(P, A) \land pw(P, X) \land \\ projection(blend, d1, X, X) \land \\ projection(blend, d2, A, A) \end{aligned}$

Transforming Frame





Knowledge Base

- Composed by Domains
- Domain:

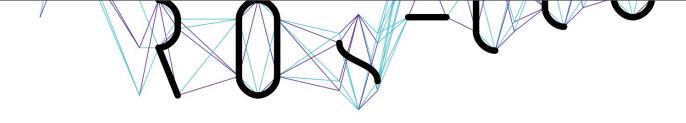
, 50 × 5((0

- Concept Map
- set of Instances
- set of Rules
- set of Frames
- set of Integrity Constraints

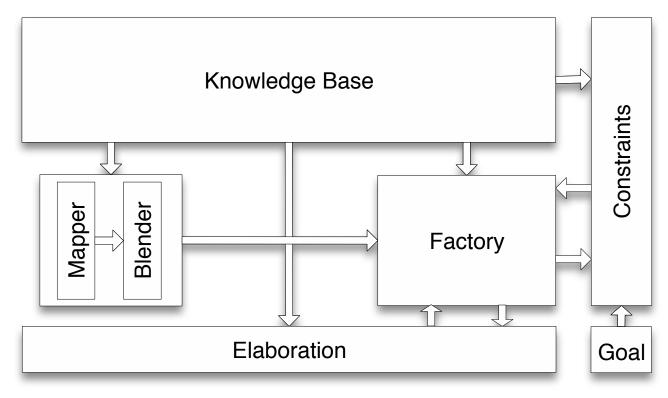
 $false \leftarrow state(X, dead) \land state(X, alive)$ $false \leftarrow pw(X, X)$

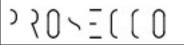


8

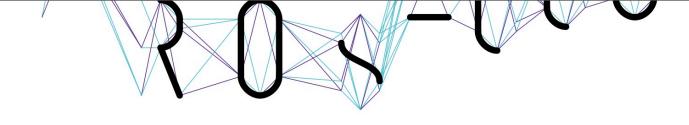


Mapping Engine







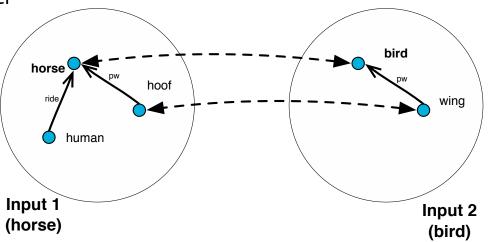


10

Mapping Engine

,50≻Ξ((O

- Structure alignment + Spreading activation
 - Similar to Sapper (Veale 93), but simpler
- Mapping: largest isomorphic pair of subgraphs
- Returns set of all possible mappings





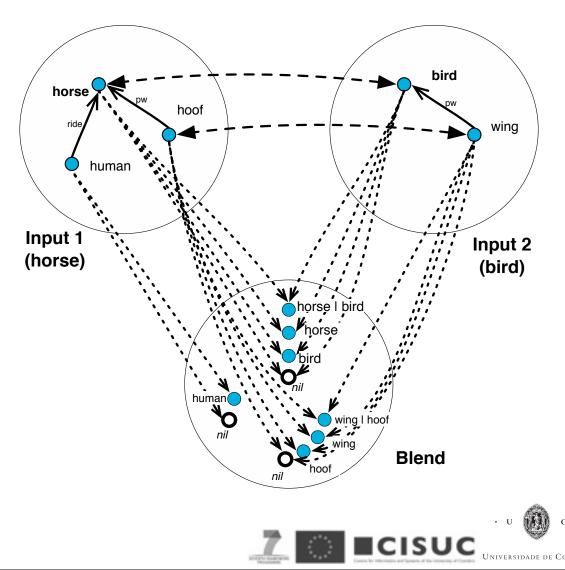


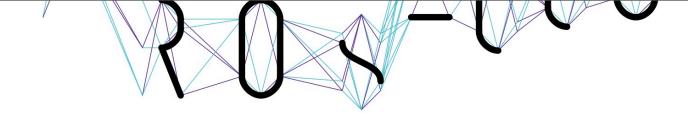
11

Blender

,5025((0

 For each mapping m, makes a blending projection



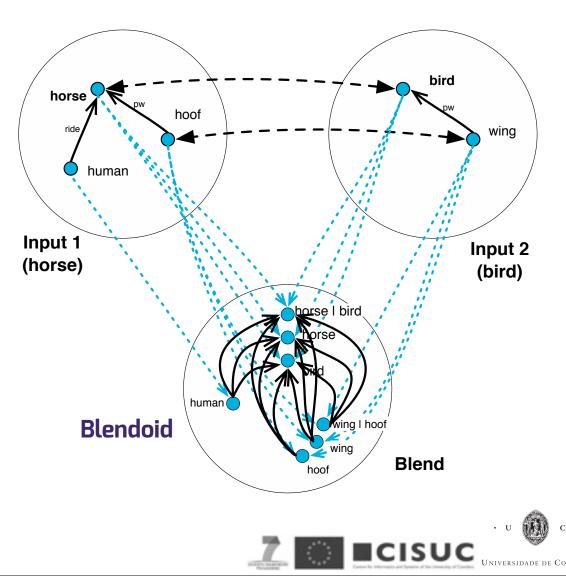


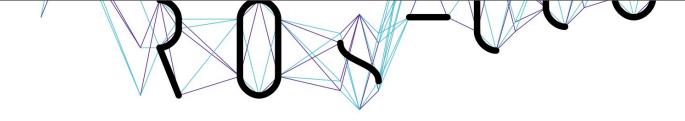
12

Blender

, 50 × 5((0

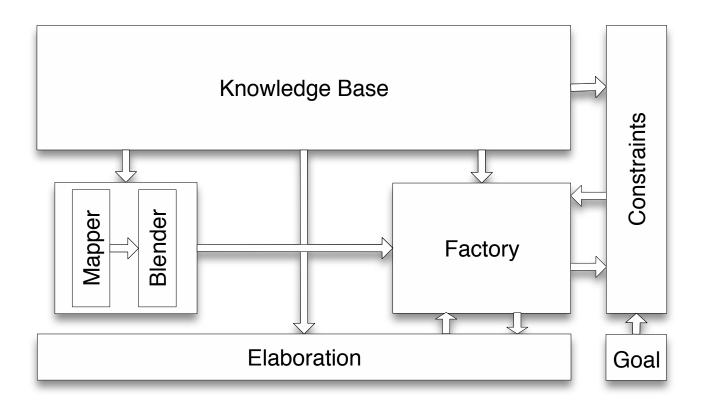
- For each mapping m, makes a blending projection
- Then, projects remaining elements in the Blend

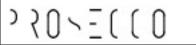




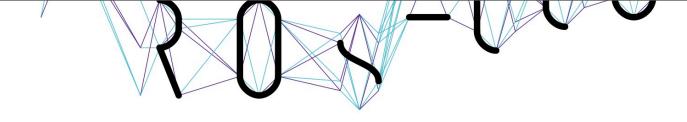
13

Factory





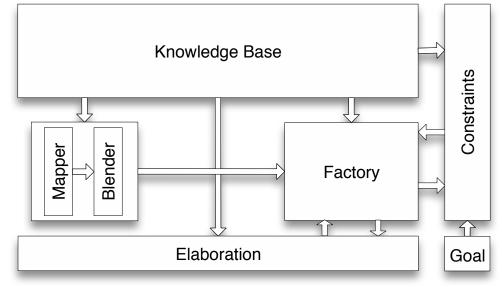




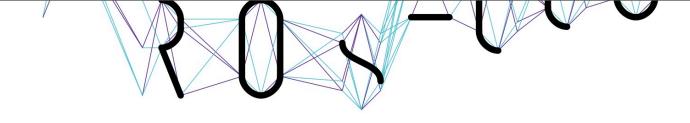
Factory

- Explores the space of all possible combinations of projections
- Divergent Strategy: GA
- Convergent Strategy
- Stoping condition

, 50 × 5((0







15

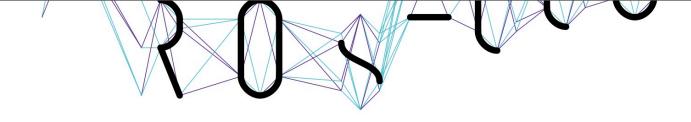
Factory

- Evolve projections:
 - individual = set of projections for each node of input domains
 - Paralell search for best blend
- Compute Blend:
 - for each individual
- Fitness function:

> 50 Z E ((0

- weighted sum of <u>optimality constraints</u>
 - 8 optimality principles (from F&T 2002)





16

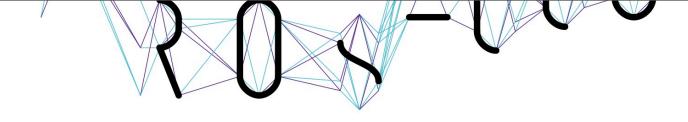
Optimality Constraints (F&T 2002)

- Integration
- Topology
- Maximization of Vital Relations
- Unpacking
- Relevance

Web

- Pattern Completion
- Intensification of Vital Relations





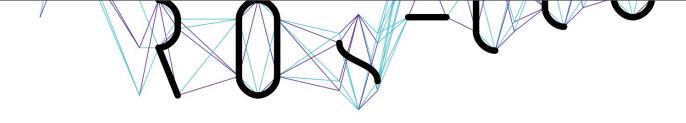
17

Elaboration

, 50 × 5((0

- Completion + Elaboration
- Run Frames, run rules

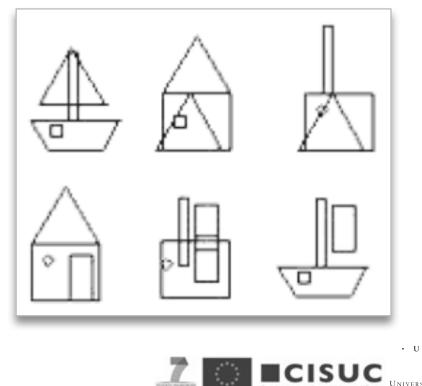




Boat-House experiment

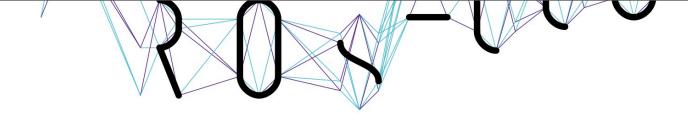
Only Concept Maps + Instances

	entrance	\leftrightarrow	movement
	task	\leftrightarrow	task
	protection	\leftrightarrow	support
	roof	\leftrightarrow	mast
	door	\leftrightarrow	sail
	house	\leftrightarrow	sailing_boat
	physical_		
	structure	\leftrightarrow	boat
	window	\leftrightarrow	hatch
	body	\leftrightarrow	vessel
	water_proof	\leftrightarrow	slow
	container	\leftrightarrow	container
2025<05°	observation	\leftrightarrow	observation
10,200			



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18

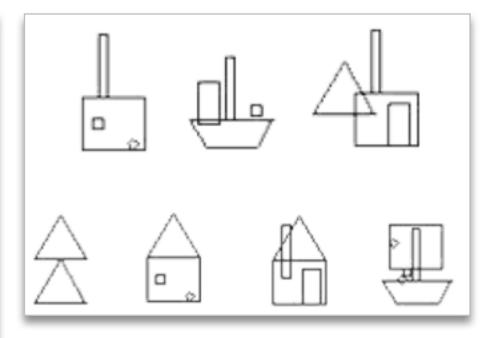


19

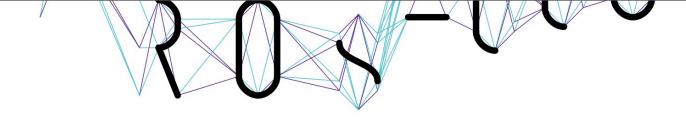
Boat-House experiment

body	\leftrightarrow	sail
container	\leftrightarrow	movement
door	\leftrightarrow	hatch
entrance	\leftrightarrow	observation
house	\leftrightarrow	sailing_boat
physical_		
structure	\leftrightarrow	boat
window	\leftrightarrow	mast
roof	\leftrightarrow	vessel
water_proof	\leftrightarrow	slow
protection	\leftrightarrow	container
observation	\leftrightarrow	support

, 50 > E((0







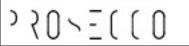
20

Creatures experiment

Input creatures





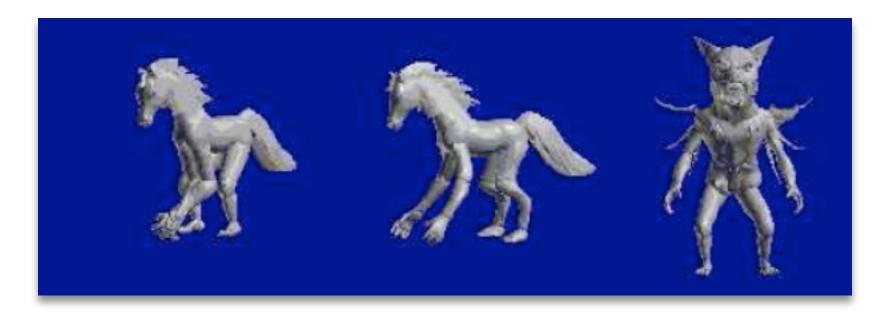




21

Creatures experiment - outputs

, 50 × 5((0



horseldragon (nov=0.25), horselwerewolf (0.56) and werewolf|dragon (0.62)





22

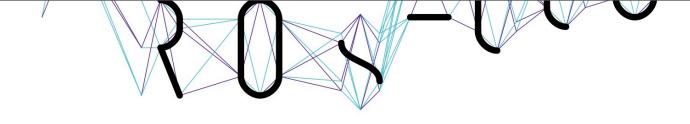
Creatures experiment - outputs

, 50 > E((0



horseldragon (0.37), horselwerewolf (0.86) and werewolf/dragon (0.65)





23

Recent approaches

) {U < -[[]

- Li, B., Zook, A., Davis, N., and Riedl, M. (2012). Goal-Driven Conceptual Blending: A Computational Approach for Creativity (ICCC12)
 - address the efficiency issues by constructing blends in a goal-driven and context-driven manner.
- Veale, T. (2012). From Conceptual "Mash-ups" to "Bad-ass" Blends: A Robust Computational Model of Conceptual Blending. (ICCC12)
 - constrained notion of Blend for creative reuse and extend existing common-sense knowledge of a topic

